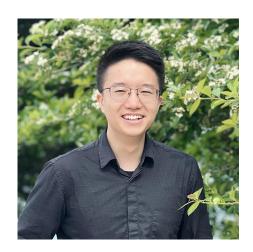
CS231n: Deep Learning for Computer Vision

Lecture 1 - Overview

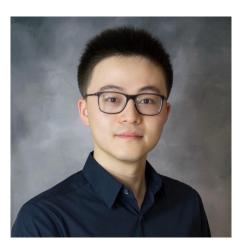
Instructors



Fei-Fei Li



Yunzhu Li



Ruohan Gao

Today's agenda

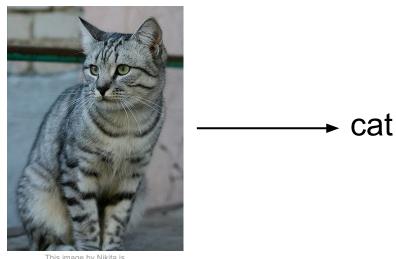
- A brief history of computer vision
- CS231n overview

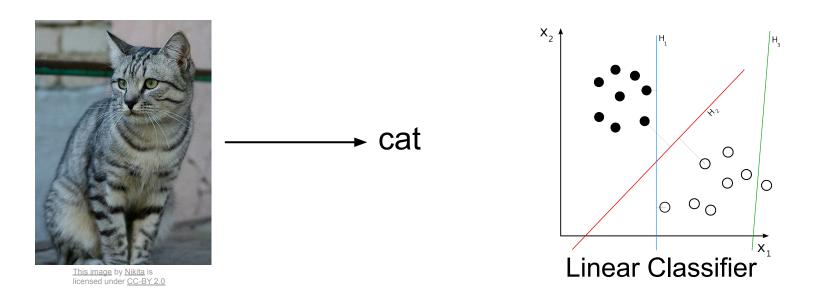
Today's agenda

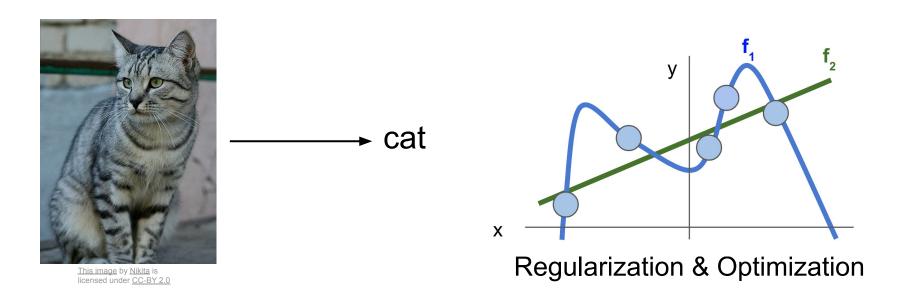
- A brief history of computer vision
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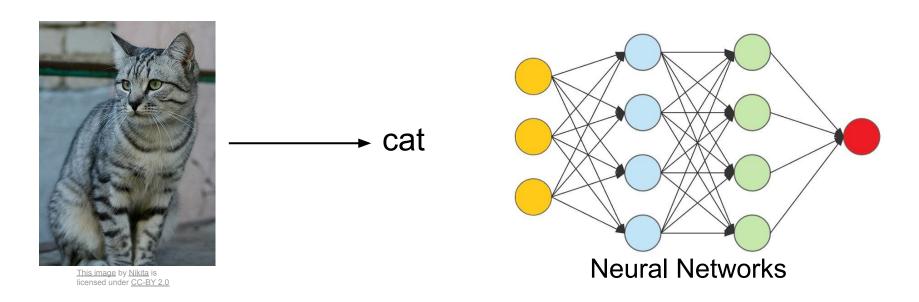
CS231n overview

- Deep Learning Basics
- Perceiving and Understanding the Visual World
- Generative and Interactive Visual Intelligence
- Human-Centered Applications and Implications









CS231n overview

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Perceiving and Understanding the Visual World



Tasks Beyond Image Classification

Classification



No spatial extent

CAT

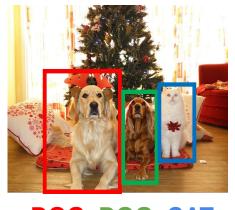
Semantic Segmentation



TREE, SKY

No objects, just pixels

Object Detection



DOG, DOG, CAT



Instance

Segmentation

DOG, DOG, CAT

Multiple Object

This image is CC0 public domain

Tasks Beyond Image Classification

Video Classification



Running? Jumping?

Multimodal Video Understanding

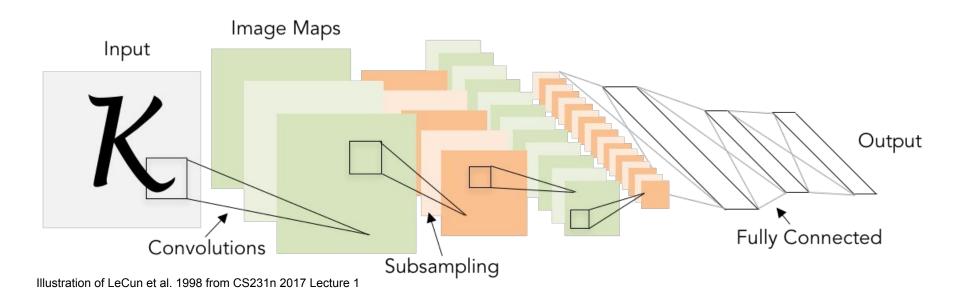


The state of the s

Visualization & Understanding

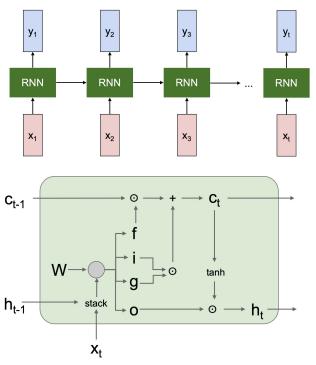


Models Beyond Multi-Layer Perceptron

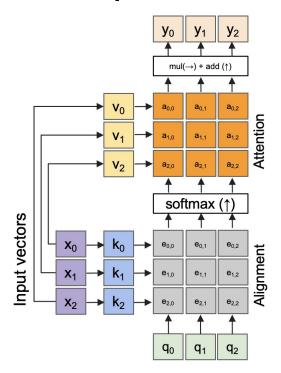


Convolutional neural network

Models Beyond Multi-Layer Perceptron



Recurrent neural network



Attention mechanism / Transformers

CS231n overview

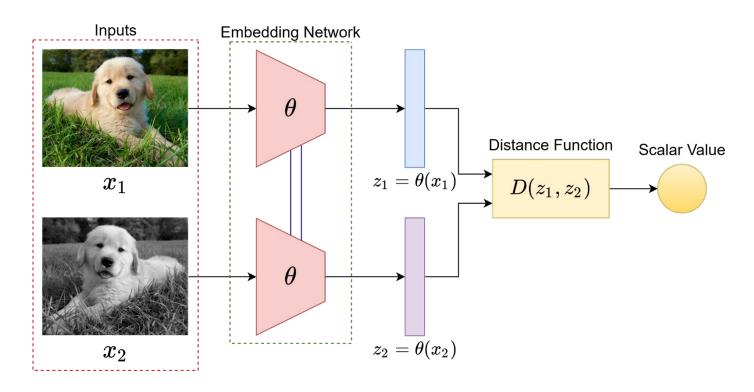
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Beyond 2D Recognition

Beyond 2D Recognition: Self-supervised Learning



Beyond 2D Recognition: Generative Modeling



"Teddy bears working on new Al research underwater with 1990s technology"

DALL-E 2

Beyond 2D Recognition: Generative Modeling





Style Transfer

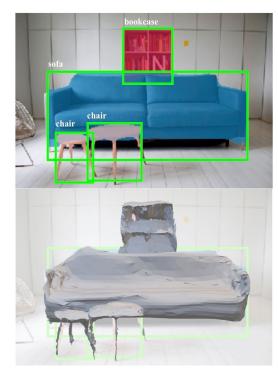
Beyond 2D Recognition: 3D Vision



Choy et al., 3D-R2N2: Recurrent Reconstruction Neural Network (2016)



Zhou et al., 3D Shape Generation and Completion through Point-Voxel Diffusion (2021)



Gkioxari et al., "Mesh R-CNN", ICCV 2019

Beyond 2D Recognition: Embodied Intelligence



Li et al., BEHAVIOR-1K: A Benchmark for Embodied AI with 1,000 Everyday Activities and Realistic Simulation (2022)



Mandlekar and Xu et al., Learning to Generalize Across Long-Horizon Tasks from Human Demonstrations (2020)

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2018 Turing Award for deep learning

most prestigious technical award, is given for major contributions of lasting importance to computing.







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IEEE PAMI Longuet-Higgins Prize

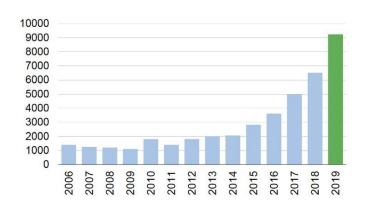
Award recognizes ONE Computer Vision paper from **ten years ago** with **significant impact on computer vision** research.

At CVPR 2019, it was awarded to the 2009 original ImageNet paper





CVPR Attendance Trend





>9k submissions, 2,360 accepted papers

Logistics

Ruohan Gao Manuka Stratta Course Manager Amelie Byun Fei-Fei Li, Yunzhu Li, Ruohan Gao

Instructors

Fei-Fei Li

Yunzhu Li



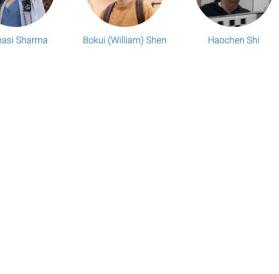












Lectures

- Tuesdays and Thursdays between 12:00 PM to 1:20 PM at NVIDIA Auditorium
- Lectures will not be streamed on Zoom but will be broadcasted live via Panopto
- Slides will be posted on the course website shortly before each lecture
- All lectures will be recorded and uploaded to <u>Canvas</u> after the lecture under the "Panopto Course Videos" Tab.

Course website [http://cs231n.stanford.edu/] - Refresh!

CS231n Home Course Notes Coursework Schedule Office Hours Lecture Videos Ed



CS231n: Deep Learning for Computer Vision



Stanford - Spring 2023

Schedule

- Lectures will occur Tuesday/Thursday from 12:00-1:20pm Pacific Time at NVIDIA Auditorium.
- Discussion sections will (generally) occur on Fridays between 1:30-2:30pm Pacific Time, location TBD. Check Ed for any exceptions.

Updated lecture slides will be posted here shortly before each lecture. For ease of reading, we have color-coded the lecture category titles in blue, discussion sections (and final project poster session) in yellow, and the midterm exam in teal. Note that the schedule is subject to change as the guarter progresses.

Date	Description	Course Materials	Events	Deadlines
04/04	Lecture 1: Introduction Computer vision overview Course overview Course logistics			
	Deep Learning Basics			
04/06	Lecture 2: Image Classification with Linear Classifiers The data-driven approach K-nearest neighbor Linear Classifiers Algebraic / Visual / Geometric viewpoints SVM and Softmax loss	Image Classification Problem Linear Classification		
04/07	Python / Numpy Review Session	⊙ 1:30-2:30pm PT	Assignment 1 out	
04/11	Lecture 3: Regularization and Optimization Regularization Stochastic Gradient Descent Momentum, AdaGrad, Adam Learning rate schedules	Optimization		

Friday Discussion Sections

6 Discussion sections Fridays 1:30 PM - 2:20 PM at Thornton 102

04/07	Python / Numpy Review Session
04/14	Backprop Review Session
04/21	Final Project Overview and Guidelines
04/28	PyTorch / TensorFlow Review Session
05/05	RNNs & Transformers
05/12	Midterm Review Session

Hands-on tutorials, with more practical details than the main lecture

Check canvas for the Zoom link of the discussion sessions!

This Friday: Python / numpy / Colab

Ed

For questions about assignments, final project, midterm, logistics, etc, use Ed!

Access: Canvas -> Deep Learning for Computer Vision -> Ed Discussion

SCPD students: Use your @stanford.edu address to register for Ed; contact scpd-customerservice@stanford.edu for help.

Office Hours

We'll be hosting both in-person and remote office hours. (starting week 2)

- Location
 - In-person: Huang basement, look for a CS231N sign
 - Remote: Zoom and QueueStatus to setup queues
 - Please see Canvas or Ed for the QueueStatus link
 - TAs will admit students to their Zoom meeting rooms for 1-1 conversations when it's your turn using QueueStatus.
- Office hour schedule is on the course website

Overview on communication

Course Website: http://cs231n.stanford.edu/

- Syllabus, lecture slides, links to assignment downloads, etc

Ed:

- Use this for most communication with course staff
- Ask questions about homework, grading, logistics, etc
- Use private questions only if your post will violate honor code if you release publicly.

Mailing list

- <u>cs231n-staff-spr23@cs.stanford.edu</u>

Gradescope:

For turning in homework and receiving grades

Canvas:

- For watching recorded lectures
- For watching recorded discussion sessions

Assignments

All assignments will be completed using Google Colab

Assignment 1: Will be out Friday 4/7, due 4/21 by 11:59 PM

- K-Nearest Neighbor
- Linear classifiers: SVM, Softmax
- Two-layer neural network
- Image features

Grading

All assignments, coding and written portions, will be submitted via **Gradescope**.

An auto-grading system:

- A consistent grading scheme
- Public tests:
 - Students see results of public tests immediately
- Private tests
 - Generalizations of the public tests to thoroughly test your implementation

Grading

3 Assignments: 10% + 20% + 15% = 45%

In-Class Midterm Exam: 20%

Course Project: 35%

- Project Proposal: 1%
- Milestone: 2%
- Final Project Report: 29%
- Poster & Poster Session: 3%

Participation Extra Credit: up to 3%

Late policy

- 4 free late days use up to 2 late days per assignment
- Afterwards, 25% off per day late
- No late days for project report

AWS

We will have AWS Cloud credits available for projects

Not for HWs (only for final projects)

We will be distributing credits to all enrolled students using your AWS account IDs

We will have a tutorial for walking through the AWS setup

Collaboration policy

We follow the <u>Stanford Honor Code</u> and the <u>CS Department Honor Code</u> – read them!

- Rule 1: Don't look at solutions or code that are not your own; everything you submit should be your own work
- Rule 2: Don't share your solution code with others; however discussing ideas
 or general strategies is fine and encouraged
- Rule 3: Indicate in your submissions anyone you worked with

Turning in something late / incomplete is better than violating the honor code

Prerequisites

Proficiency in Python

- All class assignments will be in Python (and use numpy)
- Later in the class, you will be using Pytorch and TensorFlow
- A Python tutorial available on course website

College Calculus, Linear Algebra

No longer need CS229 (Machine Learning)

Optional textbook resources

- Deep Learning
 - by Goodfellow, Bengio, and Courville
 - Here is a <u>free version</u>
- Mathematics of deep learning
 - Chapters 5, 6 7 are useful to understand vector calculus and continuous optimization
 - Free online version
- Dive into deep learning
 - An interactive deep learning book with code, math, and discussions, based on the NumPy interface.
 - Free online version

Learning objectives

Formalize computer vision applications into tasks

- Formalize inputs and outputs for vision-related problems
- Understand what data and computational requirements you need to train a model

Develop and train vision models

- Learn to code, debug, and train convolutional neural networks.
- Learn how to use software frameworks like PyTorch and TensorFlow

Gain an understanding of where the field is and where it is headed

- What new research has come out in the last 0-5 years?
- What are open research challenges?
- What ethical and societal considerations should we consider before deployment?

Why should you take this class?

Become a vision researcher (an incomplete list of conferences)

- Get involved with <u>vision research at Stanford</u>: apply <u>using this form</u>.
- CVPR 2022 conference
- ICCV 2021 conference

Become a vision engineer in industry (an incomplete list of industry teams)

- Perception team at Google AI, Vision at Google Cloud
- Vision at Meta Al
- Vision at Amazon AWS
- Nvidia, Tesla, Apple, Salesforce,

General interest

CS231n: Deep Learning for Computer Vision

- Deep Learning Basics (Lecture 2 4)
- Perceiving and Understanding the Visual World (Lecture 5 12)
- Reconstructing and Interacting with the Visual World (Lecture 13 16)
- Human-Centered Artificial Intelligence (Lecture 17 18)

Syllabus

Deep Learning Basics	Convolutional Neural Networks	Computer Vision Applications
Data-driven learning Linear classification & kNN Loss functions Optimization Backpropagation Multi-layer perceptrons Neural Networks	Convolutions PyTorch / TensorFlow Activation functions Batch normalization Transfer learning Data augmentation Momentum / RMSProp / Adam Architecture design	RNNs / Attention / Transformers Image captioning Object detection and segmentation Style transfer Video understanding Generative models Self-supervised learning 3D vision Robot learning Human-centered Al Fairness & ethics

Next time: Image classification with Linear Classifiers

k- nearest neighbor

Linear classification

